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Author's reply $\stackrel{\text{\tiny{thema}}}{\to}$

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In Ref. [1], the author studied the dynamic behaviors of a symmetric gyro with linear-plus-cubic damping mounted on a vibrating base. The system is excited by a harmonic force $\bar{\ell} \sin \omega t$. With the definitions





Fig. 1. The bifurcation diagram for x_1 in the range $32.0 \le f \le 37.0$.

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the equation of motion governing the nutation θ of the gyro is given by [1]

$$\begin{cases} \dot{x}_1 = x_2, \\ \dot{x}_2 = -\alpha^2 \frac{(1 - \cos x_1)^2}{\sin^3 x_1} - c_1 x_2 - c_2 x_2^3 + \beta \sin x_1 + f \sin \omega t \sin x_1. \end{cases}$$
(1)

The author used $x_1/4 + x_1^3/12$ to approach $(1 - \cos x_1)^2/\sin^3 x_1$ in the numerical simulation. Therefore, the critical values of f at which period doublings occur are different from the results given by Van Dooren [2]. The bifurcation diagram for specific system parameter value set $(\alpha^2 = 100, \beta = 1, c_1 = 0.5, c_2 = 0.05, \omega = 2)$ as f = 32.0-37.0 is shown in Fig. 1. At the end of the broadest zone of chaotic behavior, a 4T-solution is also obtained. It is evident that the structure of bifurcation diagram is the same as Fig. 1(a) in Ref. [2].

References

- H.-K. Chen, Chaos and chaos synchronization of a symmetric gyro with linear-plus-cubic damping, *Journal of Sound and Vibration* 255 (2000) 719–740.
- [2] R. Van Dooren, Comments on "Chaos and chaos synchronization of a symmetric gyro with linear-plus-cubic damping", Journal of Sound and Vibration 268 (3) (2003) 632–634, this issue.